PROCESS FOR REDUCING THE SECOND-ORDER NONLINEARITY OF A FREQUENCY TRANSPOSITION DEVICE AND CORRESPONDING DEVICE

Field of the Invention

[0001]   The present invention relates to frequency transposition, and more particularly, to reducing the second-order nonlinearity of a frequency transposition device or mixer. The present invention advantageously applies to wireless communication systems, and more particularly, to cellular mobile telephones.

Background of the Invention

[0002]   In a terminal of a wireless communication system, such as a cellular mobile telephone for example, direct conversion or zero intermediate frequency transposition is an alternative to a superheterodyne architecture. This is particularly well suited to allow very highly integrated architectural approaches for the terminal.

[0003]   A direct conversion receiver or a zero intermediate frequency receiver (zero-IF receiver) converts the band of the useful signal directly around the zero frequency (baseband). This is done instead of converting it to an intermediate frequency on the order of a few hundred MHz.

[0004]   Direct conversion radio frequency receivers have a drawback with respect to the second-order

nonlinearity of the input stages. Specifically, since after the mixer the band of the useful signal is centered around zero, any undesired signal, whether continuous or low frequency, is therefore a glitch or spurious signal. These spurious signals may arise in particular from the DC offset (or from the modulation of the low-frequency spurious signals) generated by input blocking signals on account of the second-order nonlinearity of the upstream stages.

[0005]   More precisely, this second-order nonlinearity may arise either from the low noise amplifier (LNA) generally connected after the antenna, or from the mixer. However, any undesired low frequency signal at the output of the low noise amplifier does not present a problem to a first approximation since the mixer will convert it to a high frequency signal. Consequently, the main problem arises from the second-order nonlinearity of the mixer itself.

[0006]   Most contemporary circuits do not use a specific design for solving the problem of the second-order nonlinearity of the mixer. These circuits generally use algorithms for monitoring these DC spurious signals. However, such algorithms are not easy to develop, and moreover, they are ineffective when the blocking signals do not induce a purely DC spurious signal, as is the case in constant envelope modulation GSM systems. Instead a low-frequency modulated spurious signal is generated, as is the case for non-constant envelope modulation systems, such as WCDMA systems.

[0007]   Designs have been proposed for addressing this problem of second-order nonlinearity of the mixer. Some of these approaches, developed in particular for constant envelope modulation systems, are based on

setting the DC offset of the mixer during production using an adjustable output load. Such an approach is described for example in the article by Alyosha Molnar, titled "A Single Chip Quad Band (850, 900, 1800, 1900 MHz) Direct Conversion GSM/GPRS RF Transceiver With Integrated VCOs And Fractional-N Synthesizer," ISSCC 2002, session 14.

[0008]   Another approach referred to as dynamic matching includes switching dynamically the inputs and the outputs so as to have a symmetric mean operation of the mixer while the mixer is operating. Such an approach is described in the article by Edwin Bautista, et al., titled "Improved Mixer IIP2 Through Dynamic Matching," ISSCC 2000, session 23, wireless building blocks paper WP 23.1.

[0009]   However, while such an approach is beneficial since it does not require an adjustment during production, it nevertheless has the drawback of requiring very good synchronization of the switching of the inputs and the outputs. This is particularly difficult to achieve since the inputs and the outputs are spaced apart on the layout on account of isolation problems. Moreover, a specific switching clock is necessary with the risk of undesired aliasing within the band of the useful signal.

Summary of the Invention

[0010]   In view of the foregoing background, an object of the present invention is to address the second-order nonlinearity problem of the mixer without requiring an adjustment to the mixer during production.

[0011]   Another object of the present invention is also to not require a specific algorithm for monitoring the DC offsets induced by the blocking signals.

[0012]   Yet another object of the present invention is to provide a mixer that is not sensitive to modulated input blocking signals. This is particularly beneficial to receivers incorporated in third generation mobile telephones.

[0013]   The present invention starts from the observation that the cause of the second-order nonlinearity of a frequency transmission device or mixer is mainly due to the electrical offset in the transistors of the current switching circuit of the mixer. Starting from this observation, the present invention proposes to calibrate this offset in the mixer itself. Stated otherwise, the present invention proposes a process for reducing the second-order nonlinearity of a frequency transposition device comprising a current switching circuit with two differential pairs of transistors controlled by a local oscillator signal.

[0014]   According to a general characteristic of the invention, the two differential pairs are statically mutually disconnected and dynamically mutually connected. The process may comprises a current switching circuit calibration mode, in which the local oscillator is rendered inactive and each of the two pairs is calibrated in succession by zeroing the ground path current of the pair not undergoing calibration and by setting the voltage difference applied to the bases of the transistors of the pair undergoing calibration until the output voltage of the frequency transposition device (that is, the output voltage of the current

switching circuit) is zeroed to within a predetermined accuracy. The base voltage difference thus obtained is stored.

[0015]   The process furthermore comprises a normal operating mode of the mixer in which the local oscillator is rendered active and the two voltage differences stored respectively on completion of the calibration mode are applied to the bases of the transistors of the two pairs. According to one mode of implementation, in the calibration mode the phase of setting the base voltage difference comprises a detection of the changing of sign of the difference in output voltage.

[0016]   The voltage difference applied to the bases of the two transistors of a pair is provided by a digital analog converter in response to a digital control word. The phase of setting the base voltage difference comprises, for example, modifying the digital control word and storing the base voltage difference obtained on completion of the calibration, and then storing the corresponding digital control word. Thus, in one mode of implementation of the invention, the digital control word will be modified, for example by a decrement from a maximum value, until the changing of the sign of the output voltage difference is detected.

[0017]   Another aspect of the present invention is directed to a frequency transposition device comprising a current switching circuit with two differential pairs of transistors controlled by a local oscillator signal. The two differential pairs may be statically mutually disconnected and dynamically mutually connected, and the device may comprises a calibration loop activated

on command. The calibration may calibrate each
differential pair by setting the voltage difference
applied to the bases of the transistors of the pair
undergoing calibration until the output voltage of the
frequency transposition device is zeroed to within a
predetermined accuracy. Storage means may store for
each pair the base voltage difference obtained after
calibration. Control means may either render the local
oscillator inactive and activate the calibration means
by zeroing the ground path current of each pair in
succession, or render the local oscillator active to
deactivate the calibration loop and to apply the two
voltage differences stored respectively in the storage
means to the bases of the transistors of the two pairs.

[0018]   According to one embodiment of the invention,
the calibration loop may comprise detection means for
detecting the changing of the sign of the output
voltage difference. The detection means may comprise a
comparator whose two inputs are linked to the two
differential outputs of the device.

[0019]   According to one embodiment of the invention,
the calibration loop comprises two digital/analog
converters respectively connected to the bases of the
transistors of the two pairs. Each converter may apply
a voltage difference to the bases of the transistors of
the corresponding pair in response to a digital control
word. Monitoring means may be connected to the output
of the detection means for formulating successive
control words until a stop signal delivered by the
detection means is received.

[0020]   Additionally, each converter preferably
delivers a voltage difference proportional to the
absolute temperature (PTAT voltage). The control means

may deactivate the calibration loop by deactivating the detection means and the monitoring means. The device according to the invention is advantageously embodied in integrated form.

[0021]   The invention is also directed to a component of a wireless communication system, for example a cellular mobile telephone, incorporating a frequency transposition device as defined hereinabove.

Brief Description of the Drawings

[0022]   Other advantages and characteristics of the present invention will become apparent on examining the detailed description of nonlimiting embodiments and modes of implementation, and of the appended drawings in which:

[0023]   Figure 1 is a block diagram partially illustrating the internal architecture of a cellular mobile telephone according to the present invention;

[0024]   Figure 2 is a schematic diagram illustrating in greater detail an embodiment of a frequency transposition device according to the present invention; and

[0025]   Figures 3 to 5 are flow charts illustrating a mode of implementation of the process according to the present invention.

Detailed Description of the Preferred Embodiments

[0026]   In Figure 1, the reference TP denotes a cellular mobile telephone incorporating frequency transposition devices or mixers MXI or MXQ according to the present invention. More precisely, the mobile telephone comprises a radio frequency stage connected

to a digital stage designed around a processor PBB and analog/digital converters ADC.

[0027]   The radio frequency stage comprises at the front end an antenna ANT followed by a low noise amplifier LNA connected to the two mixers MXI and MXQ. The two mixers MXI and MXQ belong in a conventional manner to two phase quadrature processing channels, customarily referred to as the I channel and the Q channel by those skilled in the art.

[0028]   Each mixer MXI and MXQ receives a frequency transposition signal from a local oscillator LO. A 0/90° phase shifter between the local oscillator and the mixers allows delivery to the mixer MXQ of a local oscillator signal phase-shifted by 90° with respect to the local oscillator signal delivered to the mixer MXI. Each of the mixers is followed by a controlled-gain amplifier, and by a low pass filtering stage.

[0029]   One of the mixers, for example the mixer MXI, will now be described while referring more particularly to Figure 2. The second mixer MXQ is similar to mixer MXI. The mixer MXI has a differential structure for example and comprises a current switching circuit with two differential pairs of transistors Q10, Q11 and Q20, Q21. The outputs of these transistors are coupled in a crossed manner. More precisely, the collector of the transistor Q10 and the collector of the transistor Q20 are linked together to form a first output terminal BS1. The collector of the transistor Q11 and the collector of the transistor Q21 are linked together to form a second output terminal BS2. These two output terminals form the differential output of the mixer MXI. The resistors R1 and R2 represent the load resistances of the mixer MXI.

[0030]   The base of the transistor Q10 and the base
of the transistor Q21 are linked together by two
capacitors C10 and C21 connected in series. Likewise,
the base of the transistor Q11 and the base of the
transistor Q20 are connected together by two capacitors
C11 and C20 connected in series. The midpoint of the
two capacitors C10 and C21 as well as the midpoint of
two capacitors C11 and C20 are respectively connected
to the two terminals of the differential output of the
local oscillator LO.

[0031]   The two bases of the transistors Q11 and Q20
are moreover linked together by two resistors R11 and
R20. The same holds for the bases of the transistors
Q10 and Q21 which are linked together by way of two
resistors R10 and R21. Voltage sources Vmc1 and Vmc2
allow the common mode to be monitored.

[0032]   Thus, with this arrangement, the two
differential pairs are statically mutually disconnected
but dynamically mutually connected. That is, they are
mutually connected in the presence of a radio frequency
signal at the differential input BE1-BE2 of the mixer
MXI. In this regard, an input transconductor block is
connected between the terminals BE1 and BE2 and the
collectors of the transistors of the two differential
pairs.

[0033]   In the described example, which is in no way
limiting, the input transconductor block comprises two
bipolar transistors T1 and T2 whose emitters are linked
to ground and whose respective bases are linked to the
terminals BE1 and BE2. These two transistors T1 and T2
are linked to the collectors of the two transistors
Q10-Q11 and Q20-Q21 by two cascode arrangements. A
voltage source Vref applied to the gates of the

transistors Q1 and Q2 sets the static ground path current Idc1 and Idc2 of each of the two differential pairs.

[0034] In the described example, a set of two times three breakers I11, I21, I31 and I12, I22 and I32 associated with two capacitors CP1 and CP2, as well as with two resistors RP1 and RP2, make it possible to choose between a low-gain operation or a high-gain operation.

[0035] In addition to what has just been described, the mixer comprises a calibration loop formed of a comparator CMP whose two inputs are linked respectively to the two output terminals BS1 and BS2. The output of the comparator CMP is linked to monitoring means CTL regulated by a clock signal CK, and delivers a digital control word MNC (on n bits for example) to two digital/analog converters DAC1 and DAC2.

[0036] The differential outputs of the converter DAC1 are linked to the bases of the transistors Q10 and Q11 of the first differential pair, while the differential outputs of the converter DAC2 are linked to the bases of the transistors Q1 and Q21 of the second differential pair. Thus, each converter is capable of applying a voltage difference to the bases of the corresponding transistors as a function of the control word applied to it. This control word defines a code for the converter. Control means, which may be embodied in software within the processor PBB for example, will activate or deactivate the calibration loop and the local oscillator LO.

[0037] The manner of operation of the mixer according to the invention will now be described in greater detail while referring more particularly to

Figure 3. If we consider the static behavior of the mixer, and more particularly the static behavior of each of the differential pairs taken independently of one another, then the dynamic ground path currents are zero as is the voltage delivered by the local oscillator LO which is stopped. The static current $Idc1$ of the pair Q10-Q11 for example, is in theory halved by the pair Q10-Q11.

[0038]   However, on account of the mismatch of the transistors, there is a voltage offset which is manifested at the terminals BS1 and BS2 by a non-zero output voltage Vout equal to $(-1+2\alpha)$; $RIdc1$ if we assume $R=R1=R2$. Thus, the DC output voltage Vout is an image of the defective matching α of the transistors Q10-Q11. Likewise, if we consider the pair Q20-Q21 taken in isolation, this voltage Vout is an image of the defective matching of the transistors Q20 and Q21.

[0039]   An objective of the calibration loop will then be to zero this voltage Vout for each of the differential pairs taken in isolation. More precisely, as illustrated in Figure 3, we begin for example with the calibration 30 of the pair of transistors Q10-Q11. This calibration is more particularly illustrated in Figure 4.

[0040]   For this calibration, the local oscillator LO is stopped, and the comparator CMP and the monitoring means CTL are activated. The breakers I11, I12 and I22 are open and the other breakers I21, I31 and I32 are closed. The pair Q10 and Q11 is then calibrated, and the static ground path current $Idc2$ of the pair of transistors Q20 and Q21 is zeroed. This is carried out through the configuration of the breakers.

[0041]   In the described example, the converter DAC1 is given its maximum code, for example by placing all the bits of the control word at 1. The changing of the output value of the comparator CMP will be detected (step 40). Specifically, as long as the voltage difference Vout is positive, the comparator CMP delivers the value 1 for example, whereas if this voltage difference is negative, the comparator CMP delivers the value 0.

[0042]   The changing of the output value of the comparator CMP will therefore be characteristic of the zeroing of the voltage Vout to within the accuracy of the converter DAC1. As long as the output value of the comparator CMP is not modified, the monitoring means will decrement (step 41) the control word applied to the converter DAC1. This will have the consequence of modifying the base voltage difference applied to the differential pair of transistors Q10 and Q11.

[0043]   Upon the changing of the output value of the comparator CMP, the corresponding control word will be stored (step 42), for example in a register RG1. The phase of calibration of the pair of transistors Q10 and Q11 is then terminated.

[0044]   Thereafter one proceeds as illustrated in step 31 of Figure 3 to calibration of the pair of transistors Q20 and Q21. This calibration is illustrated in greater detail in Figure 5. Only the differences with Figure 4 will now be described. For this calibration, the breaker I21 is kept open and the breaker I22 closed. Also, it is now the static ground path current Idc1 which is zeroed. Steps 50, 51 and 52 are similar to steps 40, 41 and 42.

[0045]   Upon the detection of the changing of the
output value of the comparator CMP, the corresponding
control word of the converter DAC2 is stored in a
register RG2. This marks the end of the calibration
phase of the pair Q20-Q21.

[0046]   Once this calibration mode has been
performed, we then go to a normal operating mode
(step 32). In the normal operating mode, the converters
DAC1 and DAC2 are continuously controlled by the
control words obtained on completion of the calibration
mode. Consequently, they apply respectively to the
corresponding transistor pairs the base voltage
differences allowing electrical correction of the
defective matching of the transistors of the current
switching circuit.

[0047]   In this normal operating mode, the local
oscillator LO is active. On the other hand, the
comparator CMP is inactive, as are the monitoring means
CTL (clock CK off). In the normal operating mode it is
then possible to choose a low-gain mode (step 34) in
which all the breakers I11, I21, I31, I12, I22 and I32
are closed, or else a high-gain mode in which all the
aforesaid breakers are open.

[0048]   The calibration will be performed, in the
case of a cellular mobile telephone, preferably when
the telephone is switched on, and at later instants
which will be defined by the baseband processor PBB.
This will make it possible in particular to take
account of the changing of the temperature which is a
parameter that influences the defective matching. In
this regard, it will be advantageous to provide
converters DAC1 and DAC2 incorporating a voltage source
proportional to absolute temperature (PTAT source).